

# ATLB-2180: GPS

## Cuyahoga Community College

**Viewing: ATLB-2180 : GPS**

**Board of Trustees:**

2017-06-29

**Academic Term:**

Spring 2019

**Subject Code**

ATLB - AIT-Construct/Hazard Material

**Course Number:**

2180

**Title:**

GPS

**Catalog Description:**

Advanced course covering the basic operation of the GPS and its application to the construction industry. Included are field exercises and application of related math concepts used to locate property boundaries and longitudinal and latitudinal coordinates.

**Credit Hour(s):**

2

**Lecture Hour(s):**

2

### Requisites

**Prerequisite and Corequisite**

Departmental approval: admission to Laborer's apprenticeship program.

### Outcomes

**Course Outcome(s):**

Explain the function of the global positioning system (GPS) and describe how it is used in the construction industry.

**Essential Learning Outcome Mapping:**

Critical/Creative Thinking: Analyze, evaluate, and synthesize information in order to consider problems/ideas and transform them in innovative or imaginative ways.

**Objective(s):**

1. Define the terms related to GPS operation and equipment.
2. List the applications of GPS as related to the construction industry.
3. Identify the components of the GPS and explain how they interact to establish relative grades.
4. Discuss the history of GPS and differentiate between military and civilian applications.
5. Discuss the different satellite systems and explain how they relate to each other.
6. Discuss the importance of geometric arrangement of the satellites with respect to the base station.

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**Course Outcome(s):**

Summarize how GPS is used on construction sites for locating boundaries and jobsite features.

**Essential Learning Outcome Mapping:**

Critical/Creative Thinking: Analyze, evaluate, and synthesize information in order to consider problems/ideas and transform them in innovative or imaginative ways.

**Objective(s):**

1. Explain the use of GPS files to locate proposed jobsite features.
2. Explain how property boundaries and respective right of ways are established using GPS.

3. List different pre and post jobsite features that are established using GPS.
4. Discuss how GPS is used in conjunction with earth moving equipment.

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**Course Outcome(s):**

Discuss the limitations of the GPS with respect to equipment, communication and satellite positioning.

**Essential Learning Outcome Mapping:**

Critical/Creative Thinking: Analyze, evaluate, and synthesize information in order to consider problems/ideas and transform them in innovative or imaginative ways.

**Objective(s):**

1. Explain the need to maintain the power source of the equipment.
2. Discuss the importance of good radio communication between the rover and the base.
3. Describe how high frequency signal transmission causes interference with equipment operation.
4. Explain the causes of autonomous positions and discuss the consequences to the operation.
5. Explain how positional accuracy can be increased using differential positioning.

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**Course Outcome(s):**

Demonstrate the ability to operate GPS equipment and incorporate applied math concepts to establish site coordinates.

**Essential Learning Outcome Mapping:**

Critical/Creative Thinking: Analyze, evaluate, and synthesize information in order to consider problems/ideas and transform them in innovative or imaginative ways.

**Objective(s):**

1. Set up the GPS base station over a reference point to establish accuracy between the rover and the base.
2. Power up the rover with the data collector to establish layout procedures.
3. Determine cuts and fills for jobsite using basic math concepts.
4. Operate the rover to verify building hubs and centerlines.
5. Select the respective screen on the data collector to perform required functions

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**Methods of Evaluation:**

1. Test
2. Quizzes
3. Classroom participation

**Course Content Outline:**

1. GPS and construction
  - a. Terminology
    - i. Global navigation satellite system
    - ii. Satellite
    - iii. Station
    - iv. Base station
    - v. Rover
    - vi. Data collector
    - vii. Positioning
    - viii. Orbits
    - ix. Receiver
    - x. Coordinates
    - xi. Real time kinematic
    - xii. Ambiguity
    - xiii. Multipath
    - xiv. Dilution of precision
  - b. Applications
    - i. Site layout
    - ii. Building coordinates
    - iii. Topography
    - iv. Centerline

- v. Earth moving equipment
      - vi. Cuts and fills
    - c. Components
      - i. Tripod
      - ii. Base station
      - iii. Tribrach
      - iv. Optical plummet
      - v. Receiver
      - vi. Rover
      - vii. Radio transmitter
      - viii. Satellite
    - d. History
      - i. Military
        - 1. Ivan setting
        - 2. Missile defense
        - 3. Orbiting satellites
        - 4. Block I
      - ii. Civilian
        - 1. Signal decode
        - 2. Block I and II satellites
      - iii. Applications
    - e. Satellite systems
      - i. Galileo
      - ii. Glonass
      - iii. Compass
      - iv. GPS
      - v. Relationships
        - 1. Atomic clocks
        - 2. Radio transmission
    - f. Geometric arrangement
      - i. Satellite
      - ii. Base station
      - iii. Orbits
      - iv. Triangulation accuracies
      - v. Time
- 2. GPS and construction
  - a. Boundaries
    - i. Survey
    - ii. Coordinates
    - iii. Triangulation
  - b. Right of way
  - c. Pre and post jobsite
    - i. Topography
    - ii. Civilian drawings
    - iii. Storm water
    - iv. Parking areas
  - d. Earth moving equipment
    - i. Dozers
    - ii. Track hoe
    - iii. Graders
    - iv. Milling machines
  - e. GPS files
    - i. Computer
    - ii. Construction drawings
    - iii. Math
- 3. Limitations

- a. Power source
  - i. Rechargeable batteries
  - ii. Radio loss
  - iii. Environmental
- b. Radio communication
  - i. Distance
  - ii. Frequency
  - iii. Compatible equipment
  - iv. Rover and base
- c. Interference
  - i. High frequency signals
  - ii. Electromagnetic waves
  - iii. Multipath
- d. Autonomous positioning
  - i. Radio
  - ii. Base
  - iii. Precision
  - iv. Consequences
    - 1. Equipment failure
    - 2. Inaccurate readings
- e. Positional accuracy
  - i. Differential position
  - ii. Radio
  - iii. Distances
- 4. Operation and math
  - a. Equipment set up
    - i. Tripod
    - ii. Tribrach
    - iii. Receiver
    - iv. Data collector
    - v. Control point
  - b. Rover and data collector
    - i. Power source
    - ii. Composite rod
    - iii. Operations
  - c. Cuts and fills
  - d. Verification
    - i. Building hubs
    - ii. Coordinates
    - iii. Centerlines
    - iv. Offsets
    - v. utility location
  - e. Data collector screen
    - i. Menu
      - 1. Survey
      - 2. Configuration
      - 3. Equipment
      - 4. Files
      - 5. Tools
    - ii. Math functions
      - 1. Coordinate math
      - 2. Calculations

## Resources

LIUNA Training and Education Fund. *Global Positioning Systems*". current. LIUNA Training and Education Fund ; Pomfret Center, Connecticut 06259, 2007.

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Wesley G. Crawford. *Construction Surveying and Layout*. second Edition. Creative Construction Publishing Co; West Lafayette, In. 47906, 1995.

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Leica Geosystems. "*Surveying Made Easy*". current. Leica Geosystems; Norcross, GA. 30092, 1997.

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**Resources Other**

"Construction Surveying"

<http://surveying.wb.psu.edu/psu-surv/SURIs/construction.htm>

Construction Surveying And Project Layout

<http://cset.mnsu.edu/cm/students/aic-study-guide/level1kconstsurveying.pdf>

Top of page

Key: 435